# 5b. Measure & Conquer

# COMP6741: Parameterized and Exact Computation

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#### 19T3

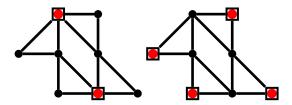
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## 1 Introduction

#### Recall: Maximal Independent Sets

- A vertex set  $S \subseteq V$  of a graph G = (V, E) is an independent set in G if there is no edge  $uv \in E$  with  $u, v \in S$ .
- An independent set is maximal if it is not a subset of any other independent set.
- Examples:

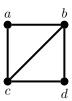


#### Enumeration problem: Enumerate all maximal independent sets

ENUM-MIS

 ${\rm Input:} \qquad {\rm graph} \ G$ 

Output: all maximal independent sets of G



Maximal independent sets:  $\{a, d\}, \{b\}, \{c\}$ 

**Note:** Let v be a vertex of a graph G. Every maximal independent set contains a vertex from  $N_G[v]$ .

### Branching Algorithm for Enum-MIS

Algorithm enum-mis(G, I)

**Input**: A graph G = (V, E), an independent set I of G.

Output: All maximal independent sets of G that are supersets of I.

$$1 G' \leftarrow G - N_G[I]$$

2 if 
$$V(G') = \emptyset$$
 then

// G' has no vertex

4 else

5 | Select 
$$v \in V(G')$$
 such that  $d_{G'}(v) = \delta(G')$ 

// v has min degree in G'

**Run enum-mis**
$$(G, I \cup \{u\})$$
 for each  $u \in N_{G'}[v]$ 

### Running Time Analysis

Let us upper bound by  $L(n) = 2^{\alpha n}$  the number of leaves in any search tree of **enum-mis** for an instance with  $|V(G')| \le n$ .

We minimize  $\alpha$  subject to constraints obtained from the branching:

$$L(n) \ge (d+1) \cdot L(n - (d+1))$$

for each integer  $d \geq 0$ .

$$\Leftrightarrow \qquad \qquad 2^{\alpha n} > d' \cdot 2^{\alpha \cdot (n - d')}$$

for each integer  $d' \geq 1$ .

$$\Leftrightarrow 1 > d' \cdot 2^{\alpha \cdot (-d')}$$

for each integer  $d' \geq 1$ .

For fixed d', the smallest value for  $2^{\alpha}$  satisfying the constraint is  $d'^{1/d'}$ . The function  $f(x) = x^{1/x}$  has its maximum value for x = e and for integer x the maximum value of f(x) is when x = 3.

Therefore, the minimum value for  $2^{\alpha}$  for which all constraints hold is  $3^{1/3}$ . We can thus set  $L(n) = 3^{n/3}$ .

Since the height of the search trees is  $\leq |V(G')|$ , we obtain:

**Theorem 1.** Algorithm enum-mis has running time  $O^*(3^{n/3}) \subseteq O(1.4423^n)$ , where n = |V|.

Corollary 2. A graph on n vertices has  $O(3^{n/3})$  maximal independent sets.

#### Running Time Lower Bound











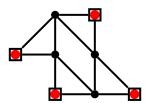
**Theorem 3.** There is an infinite family of graphs with  $\Omega(3^{n/3})$  maximal independent sets.

# 2 Maximum Independent Set

MAXIMUM INDEPENDENT SET

Input: graph G

Output: A largest independent set of G.



#### Branching Algorithm for Maximum Independent Set

```
Algorithm mis(G)
  Input: A graph G = (V, E).
  Output: The size of a maximum i.s. of G.
                                                                                 // G has max degree \leq 2
1 if \Delta(G) \leq 2 then
  return the size of a maximum i.s. of G in polynomial time
3 else if \exists v \in V : d(v) = 1 then
                                                                                         // v has degree 1
  return 1 + \mathbf{mis}(G - N[v])
5 else if G is not connected then
     Let G_1 be a connected component of G
     return mis(G_1) + mis(G - V(G_1))
8
  else
     Select v \in V s.t. d(v) = \Delta(G)
                                                             // v has max degree
9
     return \max(1 + \min(G - N[v]), \min(G - v))
```

#### Correctness

Line 4:

**Lemma 4.** If  $v \in V$  has degree 1, then G has a maximum independent set I with  $v \in I$ .

*Proof.* Let J be a maximum independent set of G. If  $v \in J$  we are done because we can take I = J. If  $v \notin J$ , then  $u \in J$ , where u is the neighbor of v, otherwise J would not be maximum. Set  $I = (J \setminus \{u\}) \cup \{v\}$ . We have that I is an independent set, and, since |I| = |J|, I is a maximum independent set containing v.

### 2.1 Simple Analysis

Lemma 5 (Simple Analysis Lemma). Let

- A be a branching algorithm
- $\alpha > 0$ , c > 0 be constants

such that on input I, A calls itself recursively on instances  $I_1, \ldots, I_k$ , but, besides the recursive calls, uses time  $O(|I|^c)$ , such that

$$(\forall i: 1 \le i \le k) \quad |I_i| \le |I| - 1, \text{ and} \tag{1}$$

$$2^{\alpha \cdot |I_1|} + \dots + 2^{\alpha \cdot |I_k|} < 2^{\alpha \cdot |I|}. \tag{2}$$

Then A solves any instance I in time  $O(|I|^{c+1}) \cdot 2^{\alpha \cdot |I|}$ .

*Proof.* By induction on |I|. W.l.o.g., suppose the hypotheses' O statements hide a constant factor  $d \ge 0$ , and for the base case assume that the algorithm returns the solution to an empty instance in time  $d \le d \cdot |I|^{c+1} 2^{\alpha \cdot |I|}$ .

Suppose the lemma holds for all instances of size at most  $|I| - 1 \ge 0$ , then the running time of algorithm A on instance I is

$$T_{A}(I) \leq d \cdot |I|^{c} + \sum_{i=1}^{k} T_{A}(I_{i})$$
 (by definition)  

$$\leq d \cdot |I|^{c} + \sum_{i=1}^{k} d \cdot |I_{i}|^{c+1} 2^{\alpha \cdot |I_{i}|}$$
 (by the inductive hypothesis)  

$$\leq d \cdot |I|^{c} + d \cdot (|I| - 1)^{c+1} \sum_{i=1}^{k} 2^{\alpha \cdot |I_{i}|}$$
 (by (1))  

$$\leq d \cdot |I|^{c} + d \cdot (|I| - 1)^{c+1} 2^{\alpha \cdot |I|}$$
 (by (2))  

$$\leq d \cdot |I|^{c+1} 2^{\alpha \cdot |I|}.$$

The final inequality uses that  $\alpha \cdot |I| > 0$  and holds for any  $c \geq 0$ .

#### Simple Analysis for mis

- At each node of the search tree:  $O(n^2)$  time
- G disconnected: (1) If  $\alpha \cdot s < 1$ , then  $s < 1/\alpha$ , and the algorithm solves  $G_1$  in constant time (provided that  $\alpha > 0$ ). We can view this rule as a simplification rule, removing  $G_1$  and making one recursive call on  $G V(G_1)$ . (2) If  $\alpha \cdot (n-s) < 1$ : similar as (1). (3) Otherwise,

$$(\forall s: 1/\alpha \le s \le n - 1/\alpha) \quad 2^{\alpha \cdot s} + 2^{\alpha \cdot (n-s)} \le 2^{\alpha \cdot n}. \tag{3}$$

always satisfied since  $2^x + 2^y \le 2^{x+y}$  if  $x, y \ge 1$ .

• Branch on vertex of degree  $d \ge 3$ 

$$(\forall d: 3 \le d \le n-1) \quad 2^{\alpha \cdot (n-1)} + 2^{\alpha \cdot (n-1-d)} \le 2^{\alpha n}. \tag{4}$$

Dividing all these terms by  $2^{\alpha n}$ , the constraints become

$$2^{-\alpha} + 2^{\alpha \cdot (-1-d)} \le 1. \tag{5}$$

### Compute optimum $\alpha$

The minimum  $\alpha$  satisfying the constraints is obtained by solving a convex mathematical program minimizing  $\alpha$  subject to the constraints (the constraint for d=3 is sufficient as all other constraints are weaker).

Alternatively, set  $x := 2^{\alpha}$ , compute the unique positive real root of each of the *characteristic polynomials* 

$$c_d(x) := x^{-1} + x^{-1-d} - 1,$$

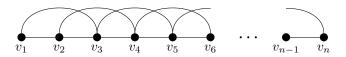
and take the maximum of these roots [Kul99].

d	$\boldsymbol{x}$	$\alpha$
3	1.3803	0.4650
4	1.3248	0.4057
5	1.2852	0.3620
6	1.2555	0.3282
7	1.2321	0.3011

#### Simple Analysis: Result

- use the Simple Analysis Lemma with c=2 and  $\alpha=0.464959$
- running time of Algorithm **mis** upper bounded by  $O(n^3) \cdot 2^{0.464959 \cdot n} = O(2^{0.4650 \cdot n})$  or  $O(1.3803^n)$

#### Lower bound



$$T(n) = T(n-5) + T(n-3)$$

- for this graph,  $P_n^2$ , the worst case running time is  $1.1938...^n \cdot \mathsf{poly}(n)$
- Run time of algo **mis** is  $\Omega(1.1938^n)$

#### Worst-case running time — a mystery

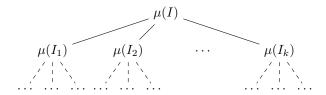
What is the worst-case running time of Algorithm mis?

- lower bound  $\Omega(1.1938^n)$
- upper bound  $O(1.3803^n)$

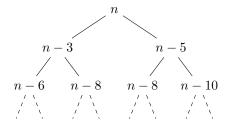
## 2.2 Search Trees and Branching Numbers

#### Search Trees

Denote  $\mu(I) := \alpha \cdot |I|$ .



Example: execution of **mis** on a  $P_n^2$ 



#### Branching number: Definition

Consider a constraint

$$2^{\mu(I)-a_1} + \dots + 2^{\mu(I)-a_k} < 2^{\mu(I)}$$
.

Its branching number is

$$2^{-a_1} + \cdots + 2^{-a_k}$$

and is denoted by

$$(a_1,\ldots,a_k)$$
.

Clearly, any constraint with branching number at most 1 is satisfied.

#### Branching numbers: Properties

**Dominance** For any  $a_i, b_i$  such that  $a_i \ge b_i$  for all  $i, 1 \le i \le k$ ,

$$(a_1,\ldots,a_k)<(b_1,\ldots,b_k)\,,$$

as 
$$2^{-a_1} + \dots + 2^{-a_k} \le 2^{-b_1} + \dots + 2^{-b_k}$$
.  
In particular, for any  $a, b > 0$ ,

either 
$$(a, a) \le (a, b)$$
 or  $(b, b) \le (a, b)$ .

**Balance** If  $0 < a \le b$ , then for any  $\varepsilon$  such that  $0 \le \varepsilon \le a$ ,

$$(a,b) < (a-\varepsilon,b+\varepsilon)$$

by convexity of  $2^x$ .

## 2.3 Measure & Conquer Analysis

- Goal
  - capture more structural changes when branching into subinstances
- How?
  - potential-function method, a.k.a., Measure & Conquer [FGK09]
- Example: Algorithm mis
  - advantage when degrees of vertices decrease

#### Measure

Instead of using the number of vertices, n, to track the progress of **mis**, let us use a measure  $\mu$  of G.

**Definition 6.** A measure  $\mu$  for a problem P is a function from the set of all instances for P to the set of non negative reals.

Let us use the following measure for the analysis of **mis** on graphs of maximum degree at most 5:

$$\mu(G) = \sum_{i=0}^{5} \omega_i n_i,$$

where  $n_i := |\{v \in V : d(v) = i\}|.$ 

#### Measure & Conquer Analysis

Lemma 7 (Measure & Conquer Lemma). Let

- A be a branching algorithm
- $c \ge 0$  be a constant, and
- $\mu(\cdot), \eta(\cdot)$  be two measures for the instances of A,

such that on input I, A calls itself recursively on instances  $I_1, \ldots, I_k$ , but, besides the recursive calls, uses time  $O(\eta(I)^c)$ , such that

$$(\forall i) \quad \eta(I_i) \le \eta(I) - 1, \text{ and} \tag{6}$$

$$2^{\mu(I_1)} + \ldots + 2^{\mu(I_k)} \le 2^{\mu(I)}. (7)$$

Then A solves any instance I in time  $O(\eta(I)^{c+1}) \cdot 2^{\mu(I)}$ .

#### Analysis of mis for degree at most 5

For  $\mu(G) = \sum_{i=0}^{5} \omega_i n_i$  to be a valid measure, we constrain that

$$w_d \ge 0$$
 for each  $d \in \{0, \dots, 5\}$ 

We also constrain that reducing the degree of a vertex does not increase the measure (useful for analysis of the degree-1 simplification rule and the branching rule):

$$-\omega_d + \omega_{d-1} \le 0 \qquad \text{for each } d \in \{1, \dots, 5\}$$

Lines 1–2 is a halting rule and we merely need that it takes polynomial time so that we can apply Lemma 7. Lines 3–4 of **mis** need to satisfy (7).

The simplification rule removes v and its neighbor u. We get a constraint for each possible degree of u:

$$2^{\mu(G)-\omega_1-\omega_d} \leq 2^{\mu(G)} \qquad \qquad \text{for each } d \in \{1,\dots,5\}$$
 
$$\Leftrightarrow \qquad \qquad 2^{-\omega_1-\omega_d} \leq 2^0 \qquad \qquad \text{for each } d \in \{1,\dots,5\}$$
 
$$\Leftrightarrow \qquad \qquad -\omega_1-\omega_d \leq 0 \qquad \qquad \text{for each } d \in \{1,\dots,5\}$$

These constraints are always satisfied since  $\omega_d \geq 0$  for each  $d \in \{0, \dots, 5\}$ . Note: the degrees of u's other neighbors (if any) decrease, but this degree change does not increase the measure.

For lines 5–7 of **mis** we consider two cases.

If  $\mu(G_1) < 1$  (or  $\mu(G - V(G_1)) < 1$ , which is handled similarly), then we view this rule as a simplification rule, which takes polynomial time to compute  $\mathbf{mis}(G_1)$ , and then makes a recursive call  $\mathbf{mis}(G - V(G_1))$ . To ensure that instances with measure < 1 can be solved in polynomial time, we constrain that

$$w_d > 0$$
 for each  $d \in \{3, 4, 5\}$ 

and this will be implied by other constraints.

Otherwise,  $\mu(G_1) \ge 1$  and  $\mu(G - V(G_1)) \ge 1$ , and we need to satisfy (7). Since  $\mu(G) = \mu(G_1) + \mu(G - V(G_1))$ , the constraints

$$2^{\mu(G_1)} + 2^{\mu(G-V(G_1))} < 2^{\mu(G)}$$

are always satisfied since the slope of the function  $2^x$  is at least 1 when  $x \ge 1$ . (I.e., we get no new constraints on  $\omega_1, \ldots, \omega_5$ .)

Lines 8–10 of **mis** need to satisfy (7). We know that in G - N[v], some vertex of  $N^2[v]$  has its degree decreased (unless G has at most 6 vertices, which can be solved in constant time). Define

$$(\forall d: 2 \le d \le 5)$$
  $h_d := \min_{2 \le i \le d} \{w_i - w_{i-1}\}$ 

We obtain the following constraints:

$$2^{\mu(G)-w_d - \sum_{i=2}^d p_i \cdot (w_i - w_{i-1})} + 2^{\mu(G)-w_d - \sum_{i=2}^d p_i \cdot w_i - h_d} \le 2^{\mu(G)}$$

$$\Leftrightarrow \qquad \qquad 2^{-w_d - \sum_{i=2}^d p_i \cdot (w_i - w_{i-1})} + 2^{-w_d - \sum_{i=2}^d p_i \cdot w_i - h_d} \le 1$$

for all  $d, 3 \le d \le 5$  (degree of v), and all  $p_i, 2 \le i \le d$ , such that  $\sum_{i=2}^{d} p_i = d$  (number of neighbors of degree i).

#### Applying the lemma

Our constraints

$$\begin{aligned} w_d &\geq 0 \\ -\omega_d + \omega_{d-1} &\leq 0 \\ 2^{-w_d - \sum_{i=2}^d p_i \cdot (w_i - w_{i-1})} + 2^{-w_d - \sum_{i=2}^d p_i \cdot w_i - h_d} &\leq 1 \end{aligned}$$

are satisfied by the following values:

i	$w_i$	$h_i$
1	0	0
2	0.25	0.25
3	0.35	0.10
4	0.38	0.03
5	0.40	0.02

These values for  $w_i$  satisfy all the constraints and  $\mu(G) \leq 2n/5$  for any graph of max degree  $\leq 5$ . Taking c=2 and  $\eta(G)=n$ , the Measure & Conquer Lemma shows that **mis** has run time  $O(n^3)2^{2n/5}=O(1.3196^n)$  on graphs of max degree  $\leq 5$ .

## 2.4 Optimizing the measure

#### Compute optimal weights

• By convex programming [GaspersS09]

All constraints are already convex, except conditions for  $h_d$ 

$$(\forall d: 2 \le d \le 5) \quad h_d := \min_{2 \le i \le d} \{w_i - w_{i-1}\}$$
 
$$\downarrow \downarrow$$
 
$$(\forall i, d: 2 \le i \le d \le 5) \quad h_d \le w_i - w_{i-1}.$$

Use existing convex programming solvers to find optimum weights.

### Convex program in AMPL

```
param maxd integer = 5;
set DEGREES := 0..maxd;
var W {DEGREES} >= 0; # weight for vertices according to their degrees
var g {DEGREES} >= 0; # weight for degree reductions from deg i
var h {DEGREES} >= 0; # weight for degree reductions from deg <= i
                                     # maximum weight of W[d]
minimize Obj: Wmax;
                                     # minimize the maximum weight
subject to MaxWeight {d in DEGREES}:
   Wmax >= W[d];
subject to gNotation {d in DEGREES : 2 <= d}:</pre>
   g[d] <= W[d]-W[d-1];
subject to hNotation {d in DEGREES, i in DEGREES : 2 <= i <= d}:</pre>
  h[d] <= W[i]-W[i-1];
h[d] <= W[i]-W[i-1];

subject to Deg3 {p2 in 0..3, p3 in 0..3 : p2+p3=3}:

2^(-W[3] -p2*g[2] -p3*g[3]) + 2^(-W[3] -p2*W[2] -p3*W[3] -h[3]) <=1;

subject to Deg4 {p2 in 0..4, p3 in 0..4, p4 in 0..4 : p2+p3+p4=4}:

2^(-W[4] - p2*g[2] - p3*g[3] - p4*g[4])

+ 2^(-W[4] - p2*W[2] - p3*W[3] - p4*W[4] - h[4]) <=1;

subject to Deg5 {p2 in 0..5, p3 in 0..5, p4 in 0..5, p5 in 0..5 :

n2*p3*p4*p5=5}:
p2+p3+p4+p5=5}:

2^(-W[5] - p2*g[2] - p3*g[3] - p4*g[4] - p5*g[5])

+ 2^(-W[5] - p2*W[2] - p3*W[3] - p4*W[4] - p5*W[5] - h[5]) <=1;
```

#### Optimal weights

i	$w_i$	$h_i$
1	0	0
2	0.206018	0.206018
3	0.324109	0.118091
4	0.356007	0.031898
5	0.358044	0.002037

- use the Measure & Conquer Lemma with  $\mu(G) = \sum_{i=1}^{5} w_i n_i \le 0.358044 \cdot n$ , c = 2, and  $\eta(G) = n$
- **mis** has running time  $O(n^3)2^{0.358044 \cdot n} = O(1.2817^n)$

#### 2.5 Exponential Time Subroutines

Lemma 8 (Combine Analysis Lemma). Let

- A be a branching algorithm and B be an algorithm,
- $c \ge 0$  be a constant, and
- $\mu(\cdot), \mu'(\cdot), \eta(\cdot)$  be three measures for the instances of A and B,

such that  $\mu'(I) \leq \mu(I)$  for all instances I, and on input I, A either solves I by invoking B with running time  $O(\eta(I)^{c+1}) \cdot 2^{\mu'(I)}$ , or calls itself recursively on instances  $I_1, \ldots, I_k$ , but, besides the recursive calls, uses time  $O(\eta(I)^c)$ , such that

$$(\forall i) \quad \eta(I_i) \le \eta(I) - 1, \text{ and} \tag{8}$$

$$2^{\mu(I_1)} + \ldots + 2^{\mu(I_k)} \le 2^{\mu(I)}. \tag{9}$$

Then A solves any instance I in time  $O(\eta(I)^{c+1}) \cdot 2^{\mu(I)}$ .

#### Algorithm mis on general graphs

- use the Combine Analysis Lemma with  $A = B = \mathbf{mis}$ , c = 2,  $\mu(G) = 0.35805n$ ,  $\mu'(G) = \sum_{i=1}^{5} w_i n_i$ , and  $\eta(G) = n$
- for every instance G,  $\mu'(G) \leq \mu(G)$  because  $\forall i, w_i \leq 0.35805$
- for each  $d \ge 6$ ,

$$(0.35805, (d+1) \cdot 0.35805) \le 1$$

• Thus, Algorithm **mis** has running time  $O(1.2817^n)$  for graphs of arbitrary degrees

## 2.6 Structures that arise rarely

#### **Rare Configurations**

- Branching on a local configuration C does not influence overall running time if C is selected only a constant number of times on the path from the root to a leaf of any search tree corresponding to the execution of the algorithm
- Can be proved formally by using measure

$$\mu'(I) := \begin{cases} \mu(I) + c & \text{if } C \text{ may be selected in the current subtree} \\ \mu(I) & \text{otherwise.} \end{cases}$$

#### Avoid branching on regular instances in mis

else

Select  $v \in V$  such that

- (1) v has maximum degree, and
- (2) among all vertices satisfying (1), v has a neighbor of minimum degree

return  $\max(1 + \mathbf{mis}(G - N[v]), \mathbf{mis}(G - v))$ 

New measure:

$$\mu'(G) = \mu(G) + \sum_{d=3}^{5} [G \text{ has a } d\text{-regular subgraph}] \cdot C_d$$

where  $C_d, 3 \le d \le 5$ , are constants. The Iverson bracket  $[F] = \begin{cases} 1 \text{ if } F \text{ true} \\ 0 \text{ otherwise} \end{cases}$ 

#### Resulting Branching numbers

For each  $d, 3 \le d \le 5$  and all  $p_i, 2 \le i \le d$  such that  $\sum_{i=2}^d p_i = d$  and  $p_d \ne d$ ,

$$\left(w_d + \sum_{i=2}^d p_i \cdot (w_i - w_{i-1}), w_d + \sum_{i=2}^d p_i \cdot w_i + h_d\right).$$

All these branching numbers are at most 1 with the optimal set of weights

#### Result

i	$w_i$	$h_i$
1	0	0
2	0.207137	0.207137
3	0.322203	0.115066
4	0.343587	0.021384
5	0.347974	0.004387

Thus, the modified Algorithm **mis** has running time  $O(2^{0.3480 \cdot n}) = O(1.2728^n)$ .

Current fastest algorithm for MIS:  $O(1.1996^n)$  [XN17]

## 3 Further Reading

- Chapter 2, Branching in [FK10]
- $\bullet$  Chapter 6, Measure & Conquer in [FK10]
- Chapter 2, Branching Algorithms in [Gas10]

## References

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