## 8a. Randomized Algorithms

# COMP6741: Parameterized and Exact Computation 

Serge Gaspers ${ }^{12}$<br>${ }^{1}$ School of Computer Science and Engineering, UNSW Sydney, Australia<br>${ }^{2}$ Decision Sciences Group, Data61, CSIRO, Australia

Semester 2, 2018

## Outline

(1) Introduction
(2) Vertex Cover
(3) Feedback Vertex Set
(4) Color Coding
(5) Monotone Local Search

## Outline

(1) Introduction

## Randomized Algorithms

- Turing machines do not inherently have access to randomness.
- Assume algorithm has also access to a stream of random bits drawn uniformly at random.
- With $r$ random bits, the probability space is the set of all $2^{r}$ possible strings of random bits (with uniform distribution).


## Las Vegas algorithms

## Definition 1

A Las Vegas algorithm is a randomized algorithm whose output is always correct.
Randomness is used to upper bound the expected running time of the algorithm.

## Example

Quicksort with random choice of pivot.

## Monte Carlo algorithms

## Definition 2

- A Monte Carlo algorithm is an algorithm whose output is incorrect with probability at most $p, 0<p<1$.
- A Monte Carlo has one sided error if its output is incorrect only on Yes-instances or on No-instances, but not both.
- A one-sided error Monte Carlo algorithm with false negatives answers No for every No-instance, and answers Yes on Yes-instances with probability $p \in(0,1)$. We say that $p$ is the success probability of the algorithm.


## Algorithms with increased success probability

## Boosting success probability

Suppose $A$ is a one-sided Monte Carlo algorithm with false negatives with success probability $p$. How can we use $A$ to design a new one-sided Monte Carlo algorithm with success probability $p^{*}>p$ ?

## Algorithms with increased success probability

## Boosting success probability

Suppose $A$ is a one-sided Monte Carlo algorithm with false negatives with success probability $p$. How can we use $A$ to design a new one-sided Monte Carlo algorithm with success probability $p^{*}>p$ ?

Let $t=-\frac{\ln \left(1-p^{*}\right)}{p}$ and run the algorithm $t$ times. Return Yes if at least one run of the algorithm returned Yes, and No otherwise.

## Algorithms with increased success probability

## Boosting success probability

Suppose $A$ is a one-sided Monte Carlo algorithm with false negatives with success probability $p$. How can we use $A$ to design a new one-sided Monte Carlo algorithm with success probability $p^{*}>p$ ?

Let $t=-\frac{\ln \left(1-p^{*}\right)}{p}$ and run the algorithm $t$ times. Return Yes if at least one run of the algorithm returned YES, and No otherwise. Failure probability is

$$
(1-p)^{t} \leq\left(e^{-p}\right)^{t}=\frac{1}{e^{p t}}=e^{\ln \left(1-p^{*}\right)}=1-p^{*}
$$

via the inequality $1-x \leq e^{-x}$.

## Algorithms with increased success probability

## Boosting success probability

Suppose $A$ is a one-sided Monte Carlo algorithm with false negatives with success probability $p$. How can we use $A$ to design a new one-sided Monte Carlo algorithm with success probability $p^{*}>p$ ?

Let $t=-\frac{\ln \left(1-p^{*}\right)}{p}$ and run the algorithm $t$ times. Return Yes if at least one run of the algorithm returned YES, and No otherwise. Failure probability is

$$
(1-p)^{t} \leq\left(e^{-p}\right)^{t}=\frac{1}{e^{p t}}=e^{\ln \left(1-p^{*}\right)}=1-p^{*}
$$

via the inequality $1-x \leq e^{-x}$.

## Definition 3

A randomized algorithm is a one-sided Monte Carlo algorithm with constant success probability.

## Amplification

## Theorem 4

If a one-sided error Monte Carlo algorithm has success probability at least $p$, then repeating it independently $\left\lceil\frac{1}{p}\right\rceil$ times gives constant success probability.

In particular if we have a polynomial-time one-sided error Monte Carlo algorithm with success probability $p=\frac{1}{f(k)}$ for some computable function $f$, then we get a randomized FPT algorithm with running time $O^{*}(f(k))$.

## Outline

(1) Introduction
(2) Vertex Cover

## (3) Feedback Vertex Set

4 Color Coding
(5) Monotone Local Search

## Vertex Cover

For a graph $G=(V, E)$ a vertex cover $X \subseteq V$ is a set of vertices such that every edge is adjacent to a vertex in $X$.

Vertex Cover
Input: Graph $G$, integer $k$
Parameter: $k$
Question: Does $G$ have a vertex cover of size $k$ ?

## Vertex Cover

For a graph $G=(V, E)$ a vertex cover $X \subseteq V$ is a set of vertices such that every edge is adjacent to a vertex in $X$.

```
Vertex Cover
    Input: Graph G}\mathrm{ , integer }
    Parameter: k
    Question: Does }G\mathrm{ have a vertex cover of size k?
```

Warm-up: design a randomized algorithm with running time $O^{*}\left(2^{k}\right)$.

## Randomized Algorithm for Vertex Cover

## Theorem 5

Vertex Cover has a randomized algorithm with running time $O^{*}\left(2^{k}\right)$.

## Proof.

- Select an edge $u v \in E$ uniformly at random.
- Select an endpoint $w \in\{u, v\}$ of that edge uniformly at random.
- Add $w$ to the partial vertex cover $S$ (initially empty).
- If $G$ has vertex cover number at most $k$, then repeating this $k$ times gives a vertex cover with probability at least $\frac{1}{2^{k}}$.
- Applying Theorem 4 gives a randomized FPT running time of $O^{*}\left(2^{k}\right)$.


## Outline

## (1) Introduction

(2) Vertex Cover
(3) Feedback Vertex Set

## 4 Color Coding

(5) Monotone Local Search

## Feedback Vertex Set

A feedback vertex set of a multigraph $G=(V, E)$ is a set of vertices $S \subset V$ such that $G-S$ is acyclic.

```
Feedback Vertex Set
    Input: Multigraph G, integer k
    Parameter: k
    Question: Does }G\mathrm{ have a feedback vertex of size }k\mathrm{ ?
```


## Feedback Vertex Set

A feedback vertex set of a multigraph $G=(V, E)$ is a set of vertices $S \subset V$ such that $G-S$ is acyclic.

```
Feedback Vertex Set
    Input: Multigraph G, integer k
    Parameter: k
    Question: Does }G\mathrm{ have a feedback vertex of size }k\mathrm{ ?
```

Recall our simplification rules for Feedback Vertex Set.

## Simplification Rules

(1) Loop: If loop at vertex $v$, remove $v$ and decrease $k$ by 1
(2) Multiedge: Reduce the multiplicity of each edge with multiplicity $\geq 3$ to 2 .
( Degree-1: If $v$ has degree at most 1 then remove $v$.
(9) Degree-2: If $v$ has degree 2 with neighbors $u, w$ then delete 2 edges $u v, v w$ and replace with new edge $u w$.
(6) Budget: If $k<0$, then return no.

## The solution is incident to a constant fraction of the edges

## Lemma 6

Let $G$ be a multigraph with minimum degree at least 3. Then, for every feedback vertex set $X$ of $G$, at least $1 / 3$ of the edges have at least one endpoint in $X$.

## The solution is incident to a constant fraction of the edges

## Lemma 6

Let $G$ be a multigraph with minimum degree at least 3. Then, for every feedback vertex set $X$ of $G$, at least $1 / 3$ of the edges have at least one endpoint in $X$.

## Proof.

Denote by $n$ and $m$ the number of vertices and edges of $G$, respectively. Since $\delta(G) \geq 3$, we have that $m \geq 3 n / 2$.
Let $F:=G-X$.
Since $F$ has at most $n-1$ edges, at least $\frac{1}{3}$ of the edges have an endpoint in $X$.

## Randomized Algorithm

## Theorem 7

Feedback Vertex Set has a randomized algorithm with running time $O^{*}\left(6^{k}\right)$.

## Randomized Algorithm

## Theorem 7

Feedback Vertex Set has a randomized algorithm with running time $O^{*}\left(6^{k}\right)$.
We prove the theorem using the following algorithm.

- $S \leftarrow \emptyset$
- Do $k$ times: Apply simplification rules; add a random endpoint of a random edge to $S$.
- If $S$ is a feedback vertex set, return Yes, otherwise return No.


## Proof

## Proof.

- We need to show: each time the algorithm adds a vertex $v$ to $S$, if $(G-S, k-|S|)$ is a Yes-instance, then with probability at least $1 / 6$, the instance $(G-(S \cup\{v\}), k-|S|-1)$ is also a Yes-instance. Then, by induction, we can conclude that with probability $1 /\left(6^{k}\right)$, the algorithm finds a feedback vertex set of size at most $k$ if it is given a Yes-instance.


## Proof

## Proof.

- We need to show: each time the algorithm adds a vertex $v$ to $S$, if ( $G-S, k-|S|$ ) is a Yes-instance, then with probability at least $1 / 6$, the instance $(G-(S \cup\{v\}), k-|S|-1)$ is also a Yes-instance. Then, by induction, we can conclude that with probability $1 /\left(6^{k}\right)$, the algorithm finds a feedback vertex set of size at most $k$ if it is given a Yes-instance.
- Assume $(G-S, k-|S|)$ is a Yes-instance.
- Lemma 6 implies that with probability at least $1 / 3$, a randomly chosen edge $u v$ has at least one endpoint in some feedback vertex set of size $k-|S|$.
- So, with probability at least $\frac{1}{2} \cdot \frac{1}{3}=\frac{1}{6}$, a randomly chosen endpoint of $u v$ belongs some feedback vertex set.


## Proof

## Proof.

- We need to show: each time the algorithm adds a vertex $v$ to $S$, if ( $G-S, k-|S|$ ) is a Yes-instance, then with probability at least $1 / 6$, the instance $(G-(S \cup\{v\}), k-|S|-1)$ is also a Yes-instance. Then, by induction, we can conclude that with probability $1 /\left(6^{k}\right)$, the algorithm finds a feedback vertex set of size at most $k$ if it is given a Yes-instance.
- Assume $(G-S, k-|S|)$ is a Yes-instance.
- Lemma 6 implies that with probability at least $1 / 3$, a randomly chosen edge $u v$ has at least one endpoint in some feedback vertex set of size $k-|S|$.
- So, with probability at least $\frac{1}{2} \cdot \frac{1}{3}=\frac{1}{6}$, a randomly chosen endpoint of $u v$ belongs some feedback vertex set.
- Applying Theorem 4 gives a randomized FPT running time of $O^{*}\left(6^{k}\right)$.


## Improved analysis

## Lemma 8

Let $G$ be a multigraph with minimum degree at least 3 . For every feedback vertex set $X$, at least $\frac{1}{2}$ of the edges of $G$ have at least one endpoint in $X$.

## Improved analysis

## Lemma 8

Let $G$ be a multigraph with minimum degree at least 3 . For every feedback vertex set $X$, at least $\frac{1}{2}$ of the edges of $G$ have at least one endpoint in $X$.

Note: For a feedback vertex set $X$, consider the forest $F:=G-X$. The statement is equivalent to:

$$
|E(G) \backslash E(F)| \geq|E(F)|
$$

Let $J \subseteq E(G)$ denote the edges with one endpoint in $X$, and the other in $V(F)$. We will show the stronger result:

$$
|J| \geq|V(F)|
$$

## Improved analysis

## Proof.

- Let $V_{\leq 1}, V_{2}, V_{\geq 3}$ be the set of vertices that have degree at most 1 , exactly 2 , and at least 3, respectively, in $F$.


## Improved analysis

## Proof.

- Let $V_{\leq 1}, V_{2}, V_{\geq 3}$ be the set of vertices that have degree at most 1 , exactly 2 , and at least 3 , respectively, in $F$.
- Since $\delta(G) \geq 3$, each vertex in $V_{\leq 1}$ contributes at least 2 edges to $J$, and each vertex in $V_{2}$ contributes at least 1 edge to $J$.


## Improved analysis

## Proof.

- Let $V_{\leq 1}, V_{2}, V_{\geq 3}$ be the set of vertices that have degree at most 1 , exactly 2 , and at least 3 , respectively, in $F$.
- Since $\delta(G) \geq 3$, each vertex in $V_{\leq 1}$ contributes at least 2 edges to $J$, and each vertex in $V_{2}$ contributes at least 1 edge to $J$.
- We show that $\left|V_{\geq 3}\right| \leq\left|V_{\leq 1}\right|$ by induction on $|V(F)|$.
- Trivially true for forests with at most 1 vertex.
- Assume true for forests with at most $n-1$ vertices.
- For any forest on $n$ vertices, consider removing a leaf (which must always exist) to obtain $F^{\prime}$ with the vertex partition $\left(V_{\leq 1}^{\prime}, V_{2}^{\prime}, V_{\geq 3}^{\prime}\right)$. If $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right|$, then we have that $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right| \leq\left|V_{\leq 1}^{\prime}\right| \leq\left|V_{\geq 1}\right|$. Otherwise, $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right|+1 \leq\left|V_{\leq 1}^{\prime}\right|+1=\left|V_{\leq 1}\right|$.


## Improved analysis

## Proof.

- Let $V_{\leq 1}, V_{2}, V_{\geq 3}$ be the set of vertices that have degree at most 1 , exactly 2 , and at least 3 , respectively, in $F$.
- Since $\delta(G) \geq 3$, each vertex in $V_{\leq 1}$ contributes at least 2 edges to $J$, and each vertex in $V_{2}$ contributes at least 1 edge to $J$.
- We show that $\left|V_{\geq 3}\right| \leq\left|V_{\leq 1}\right|$ by induction on $|V(F)|$.
- Trivially true for forests with at most 1 vertex.
- Assume true for forests with at most $n-1$ vertices.
- For any forest on $n$ vertices, consider removing a leaf (which must always exist) to obtain $F^{\prime}$ with the vertex partition $\left(V_{\leq 1}^{\prime}, V_{2}^{\prime}, V_{\geq 3}^{\prime}\right)$. If $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right|$, then we have that $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right| \leq\left|V_{\leq 1}^{\prime}\right| \leq\left|V_{\geq 1}\right|$. Otherwise, $\left|V_{\geq 3}\right|=\left|V_{\geq 3}^{\prime}\right|+1 \leq\left|V_{\leq 1}^{\prime}\right|+1=\left|V_{\leq 1}\right|$.
- We conclude that:

$$
|E(G) \backslash E(F)| \geq|J| \geq 2\left|V_{\leq 1}\right|+\left|V_{2}\right| \geq\left|V_{\leq 1}\right|+\left|V_{2}\right|+\left|V_{\geq 3}\right|=|V(F)|
$$

## Improved Randomized Algorithm

## Theorem 9

Feedback Vertex Set has a randomized algorithm with running time $O^{*}\left(4^{k}\right)$.

## Note

This algorithmic method is applicable whenever the vertex set we seek is incident to a constant fraction of the edges.

## Outline

## (1) Introduction

(2) Vertex Cover
(3) Feedback Vertex Set

4 Color Coding
(5) Monotone Local Search

## Longest Path

```
Longest Path
    Input: Graph G, integer k
    Parameter: k
    Question: Does }G\mathrm{ have a path on }k\mathrm{ vertices as a subgraph?
```


## Longest Path

```
LONGEST Path
    Input: Graph G, integer k
    Parameter: k
    Question: Does }G\mathrm{ have a path on }k\mathrm{ vertices as a subgraph?
```


## NP-complete

To show that Longest Path is NP-hard, reduce from Hamiltonian Path by setting $k=n$ and leaving the graph unchanged.

## Color Coding

## Lemma 10

Let $U$ be a set of size $n$, and let $X \subseteq U$ be a subset of size $k$. Let $\chi: U \rightarrow[k]$ be a coloring of the elements of $U$, chosen uniformly at random. Then the probability that the elements of $X$ are colored with pairwise distinct colors is at least $e^{-k}$.

## Color Coding

## Lemma 10

Let $U$ be a set of size $n$, and let $X \subseteq U$ be a subset of size $k$. Let $\chi: U \rightarrow[k]$ be a coloring of the elements of $U$, chosen uniformly at random. Then the probability that the elements of $X$ are colored with pairwise distinct colors is at least $e^{-k}$.

## Proof.

There are $k^{n}$ possible colorings $\chi$ and $k!k^{n-k}$ of them are injective on $X$. Using the inequality

$$
k!>(k / e)^{k},
$$

the lemma follows since

$$
\frac{k!\cdot k^{n-k}}{k^{n}}>\frac{k^{k} \cdot k^{n-k}}{e^{k} \cdot k^{n}}=e^{-k} .
$$

## Colorful Path

A path is colorful if all vertices of the path are colored with pairwise distinct colors.

## Lemma 11

Let $G$ be an undirected graph, and let $\chi: V(G) \rightarrow[k]$ be a coloring of its vertices with $k$ colors. There is an algorithm that checks in time $O^{*}\left(2^{k}\right)$ whether $G$ contains a colorful path on $k$ vertices.

## Colorful Path II

## Proof.

Partition $V(G)$ into $V_{1}, \ldots, V_{k}$ subsets such that vertices in $V_{i}$ are colored $i$.

## Colorful Path II

## Proof.

Partition $V(G)$ into $V_{1}, \ldots, V_{k}$ subsets such that vertices in $V_{i}$ are colored $i$. Apply dynamic programming on nonempty $S \subseteq\{1, \ldots, k\}$. For $u \in \bigcup_{i \in S} V_{i}$ let $P(S, u)=$ true if there is a colorful path with colors from $S$ and $u$ as an endpoint.

## Colorful Path II

## Proof.

Partition $V(G)$ into $V_{1}, \ldots, V_{k}$ subsets such that vertices in $V_{i}$ are colored $i$. Apply dynamic programming on nonempty $S \subseteq\{1, \ldots, k\}$. For $u \in \bigcup_{i \in S} V_{i}$ let $P(S, u)=$ true if there is a colorful path with colors from $S$ and $u$ as an endpoint. We have the following:

- For $|S|=1, P(S, u)=$ true for $u \in V(G)$ iff $S=\{\chi(u)\}$.
- For $|S|>1$

$$
P(S, u)= \begin{cases}\bigvee_{u v \in E(G)} P(S \backslash\{\chi(u)\}, v) & \text { if } \chi(u) \in S \\ \text { false } & \text { otherwise }\end{cases}
$$

## Colorful Path II

## Proof.

Partition $V(G)$ into $V_{1}, \ldots, V_{k}$ subsets such that vertices in $V_{i}$ are colored $i$. Apply dynamic programming on nonempty $S \subseteq\{1, \ldots, k\}$. For $u \in \bigcup_{i \in S} V_{i}$ let $P(S, u)=$ true if there is a colorful path with colors from $S$ and $u$ as an endpoint. We have the following:

- For $|S|=1, P(S, u)=$ true for $u \in V(G)$ iff $S=\{\chi(u)\}$.
- For $|S|>1$

$$
P(S, u)= \begin{cases}\bigvee_{u v \in E(G)} P(S \backslash\{\chi(u)\}, v) & \text { if } \chi(u) \in S \\ \text { false } & \text { otherwise }\end{cases}
$$

All values of $P$ can be computed in $O^{*}\left(2^{k}\right)$ time and there exists a colorful $k$-path iff $P([k], v)$ is true for some vertex $v \in V(G)$.

## Longest Path

## Theorem 12

Longest Path has a randomized algorithm with running time $O^{*}\left((2 \cdot e)^{k}\right)$.

## Note

This algorithmic method is applicable whenever we seek a vertex set of size $O(f(k))$ that has constant treewidth.

## Outline

## (1) Introduction

(2) Vertex Cover
(3) Feedback Vertex Set

4 Color Coding
(5) Monotone Local Search

## Exponential-time algorithms and parameterized algorithms

Exponential-time algorithms

- Algorithms for NP-hard problems
- Beat brute-force \& improve
- Running time measured in the size of the universe $n$
- $O\left(2^{n} \cdot n\right), O\left(1.5086^{n}\right), O\left(1.0892^{n}\right)$


## Parameterized algorithms

- Algorithms for NP-hard problems
- Use a parameter $k$ (often $k$ is the solution size)
- Algorithms with running time $f(k) \cdot n^{c}$
- $k^{k} n^{O(1)}, 5^{k} n^{O(1)}, O\left(1.2738^{k}+k n\right)$

Can we use Parameterized algorithms to design fast Exponential-time algorithms?

## Example: Feedback Vertex Set

## $S \subseteq V$ is a feedback vertex set in a graph $G=(V, E)$ if $G-S$ is acyclic.

Feedback Vertex Set
Input: $\quad$ Graph $G=(V, E)$, integer $k$
Parameter: $k$
Question: Does $G$ have a feedback vertex set of size at most $k$ ?


## Example: Feedback Vertex Set

$$
S \subseteq V \text { is a feedback vertex set in a graph } G=(V, E) \text { if } G-S \text { is acyclic. }
$$

Feedback Vertex Set
Input: $\quad$ Graph $G=(V, E)$, integer $k$
Parameter: $k$
Question: Does $G$ have a feedback vertex set of size at most $k$ ?


## Exponential-time algorithms

- $O^{*}\left(2^{n}\right)$ trivial
- $O\left(1.8899^{n}\right)$ [Razgon 06]
- $O\left(1.7548^{n}\right)$ [Fomin, Gaspers, Pyatkin 06]
- $O\left(1.7356^{n}\right)$ [Xiao, Nagamoshi 13]
- $O\left(1.7347^{n}\right)$ [Fomin, Todinca, Villanger 15]
- $O^{*}\left(\left(17 k^{4}\right)!\right)$ [Bodlaender 94]
- $O^{*}\left((2 k+1)^{k}\right)$ [Downey, Fellows 98]
- $O^{*}\left(3.591^{k}\right)$ [Kociumaka, Pilipczuk 14]
- $O^{*}\left(3^{k}\right)(\mathrm{r})$ [Cygan 11]


## Parameterized algorithms

 $\vdots$
## Exponential-time algorithms via parameterized algorithms

## Binomial coefficients

$$
\underset{0 \leq k \leq n}{\arg \max }\binom{n}{k}=n / 2 \quad \text { and } \quad\binom{n}{n / 2}=\Theta\left(2^{n} / \sqrt{n}\right)
$$

## Exponential-time algorithms via parameterized algorithms

## Binomial coefficients

$\underset{0 \leq k \leq n}{\arg \max }\binom{n}{k}=n / 2 \quad$ and $\quad\binom{n}{n / 2}=\Theta\left(2^{n} / \sqrt{n}\right)$

## Algorithm for Feedback Vertex Set

- Set $t=0.60909 \cdot n$
- If $k \leq t$, run $O^{*}\left(3^{k}\right)$ algorithm
- Else check all $\binom{n}{k}$ vertex subsets of size $k$

Running time: $O^{*}\left(\max \left(3^{t},\binom{n}{t}\right)\right)=O^{*}\left(1.9526^{n}\right)$

## Exponential-time algorithms via parameterized algorithms

## Binomial coefficients

$\underset{0 \leq k \leq n}{\arg \max }\binom{n}{k}=n / 2 \quad$ and $\quad\binom{n}{n / 2}=\Theta\left(2^{n} / \sqrt{n}\right)$

## Algorithm for Feedback Vertex Set

- Set $t=0.60909 \cdot n$
- If $k \leq t$, run $O^{*}\left(3^{k}\right)$ algorithm
- Else check all $\binom{n}{k}$ vertex subsets of size $k$

Running time: $O^{*}\left(\max \left(3^{t},\binom{n}{t}\right)\right)=O^{*}\left(1.9526^{n}\right)$
This approach gives algorithms faster than $O^{*}\left(2^{n}\right)$ for subset problems with a parameterized algorithm faster than $O^{*}\left(4^{k}\right)$.

## Subset Problems

An implicit set system is a function $\Phi$ with:

- Input: instance $I \in\{0,1\}^{*},|I|=N$
- Output: set system $\left(U_{I}, \mathcal{F}_{I}\right)$ :
- universe $U_{I},\left|U_{I}\right|=n$
- family $\mathcal{F}_{I}$ of subsets of $U_{I}$


## Subset Problems

An implicit set system is a function $\Phi$ with:

- Input: instance $I \in\{0,1\}^{*},|I|=N$
- Output: set system $\left(U_{I}, \mathcal{F}_{I}\right)$ :
- universe $U_{I},\left|U_{I}\right|=n$
- family $\mathcal{F}_{I}$ of subsets of $U_{I}$

```
\Phi-SubSET
    Input: Instance I
    Question: Is }|\mp@subsup{\mathcal{F}}{I}{}|>0\mathrm{ ?
```


## Subset Problems

An implicit set system is a function $\Phi$ with:

- Input: instance $I \in\{0,1\}^{*},|I|=N$
- Output: set system $\left(U_{I}, \mathcal{F}_{I}\right)$ :
- universe $U_{I},\left|U_{I}\right|=n$
- family $\mathcal{F}_{I}$ of subsets of $U_{I}$


## $\Phi$-Subset

| Input: | Instance I |
| :--- | :--- |
| Question: | Is $\left\|\mathcal{F}_{I}\right\|>0$ ? |

$\Phi$-EXTENSION
Input: $\quad$ Instance $I$, a set $X \subseteq U_{I}$, and an integer $k$
Question: Does there exist a subset $S \subseteq\left(U_{I} \backslash X\right)$ such that $S \cup X \in \mathcal{F}_{I}$ and $|S| \leq k$ ?

## Algorithm

Suppose $\Phi$-Extension has a $O^{*}\left(c^{k}\right)$ time algorithm $B$.
Algorithm for checking whether $\mathcal{F}_{I}$ contains a set of size $k$

- Set $t=\max \left(0, \frac{c k-n}{c-1}\right)$
- Uniformly at random select a subset $X \subseteq U_{I}$ of size $t$
- Run $B(I, X, k-t)$


## Algorithm

Suppose $\Phi$-Extension has a $O^{*}\left(c^{k}\right)$ time algorithm $B$.

## Algorithm for checking whether $\mathcal{F}_{I}$ contains a set of size $k$

- Set $t=\max \left(0, \frac{c k-n}{c-1}\right)$
- Uniformly at random select a subset $X \subseteq U_{I}$ of size $t$
- Run $B(I, X, k-t)$

Running time: [Fomin, Gaspers, Lokshtanov, Saurabh 16]

$$
O^{*}\left(\frac{\binom{n}{t}}{\binom{k}{t}} \cdot c^{k-t}\right)=O^{*}\left(2-\frac{1}{c}\right)^{n}
$$

## Intuition

## Brute-force randomized algorithm

- Pick $k$ elements of the universe one-by-one.
- Suppose $\mathcal{F}_{I}$ contains a set of size $k$.

Success probability:

$$
\begin{gathered}
\frac{k}{n} \cdot \frac{k-1}{n-1} \cdot \ldots \cdot \frac{k-t}{n-t} \cdot \ldots \cdot \frac{2}{n-(k-2)} \frac{1}{n-(k-1)}=\frac{1}{\binom{n}{k}} \\
\quad \begin{array}{l}
\frac{1}{c}
\end{array}
\end{gathered}
$$

## Randomized Monotone Local Search

## Theorem 13 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

If there exists a (randomized) algorithm for $\Phi$-Extension with running time $O^{*}\left(c^{k}\right)$ then there exists a randomized algorithm for $\Phi$-SuBSET with running time $\left(2-\frac{1}{c}\right)^{n} \cdot N^{O(1)}$.

## Randomized Monotone Local Search

## Theorem 13 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

If there exists a (randomized) algorithm for $\Phi$-Extension with running time $O^{*}\left(c^{k}\right)$ then there exists a randomized algorithm for $\Phi$-Subset with running time $\left(2-\frac{1}{c}\right)^{n} \cdot N^{O(1)}$.

## Theorem 14 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

Feedback Vertex Set has a randomized algorithm with running time $O^{*}\left(\left(2-\frac{1}{3}\right)^{n}\right) \subseteq O\left(1.6667^{n}\right)$.

## Derandomization

Derandomization at the expense of a subexponential factor in the running time.

## Theorem 15 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

If there exists an algorithm for $\Phi$-Extension with running time $O^{*}\left(c^{k}\right)$ then there exists an algorithm for $\Phi$-SUBSET with running time $\left(2-\frac{1}{c}\right)^{n+o(n)} \cdot N^{O(1)}$.

## Derandomization

Derandomization at the expense of a subexponential factor in the running time.

## Theorem 15 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

If there exists an algorithm for $\Phi$-Extension with running time $O^{*}\left(c^{k}\right)$ then there exists an algorithm for $\Phi$-SUBSET with running time $\left(2-\frac{1}{c}\right)^{n+o(n)} \cdot N^{O(1)}$.

## Theorem 16 ([Fomin, Gaspers, Lokshtanov, Saurabh 16])

Feedback Vertex Set has an algorithm with running time $O^{*}\left(\left(2-\frac{1}{3.591}\right)^{n}\right) \subseteq O\left(1.7216^{n}\right)$.

## Multivariate Subroutines

## Theorem 17 ([Gaspers, Lee 17])

If there exists an algorithm for $\Phi$-Extension with running time $O^{*}\left(b^{n-|X|} \cdot c^{k}\right)$ then there exists an algorithm for $\Phi$-SUBSET with running time $\left(1+b-\frac{1}{c}\right)^{n+o(n)} \cdot N^{O(1)}$.

## Theorem 18 ([Gaspers, Lee 17])

Feedback Vertex Set Extension can be solved in time $O\left(1.5422^{n-|X|} 1.2041^{k}\right)$.

## Corollary 19 ([Gaspers, Lee 17])

Feedback Vertex Set can be solved in time $O\left(1.7117^{n}\right)$.

## Further Reading

- Chapter 5, Randomized methods in parameterized algorithms by Marek Cygan, Fedor V. Fomin, Łukasz Kowalik, Daniel Lokshtanov, Dániel Marx, Marcin Pilipczuk, Michał Pilipczuk, and Saket Saurabh. Parameterized Algorithms. Springer, 2015.
- Exact Algorithms via Monotone Local Search, by Fedor V. Fomin, Serge Gaspers, Daniel Lokshtanov, Saket Saurabh. Proceedings of the 48th ACM Symposium on Theory of Computing (STOC 2016), ACM, pages 764-775, 2016.
- Exact Algorithms via Multivariate Subroutines, by Serge Gaspers and Edward J. Lee. Proceedings of the 44th International Colloquium on Automata, Languages and Programming (ICALP 2017), Track A. Schloss Dagstuhl - Leibniz-Zentrum fuer Informatik, LIPIcs 80, pages 69:1-69:13, 2017.

