# 8a. Randomized Algorithms

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# 1 Introduction

## Randomized Algorithms

- Turing machines do not inherently have access to randomness.
- Assume algorithm has also access to a stream of *random bits* drawn uniformly at random.
- With r random bits, the probability space is the set of all  $2^r$  possible strings of random bits (with uniform distribution).

## Las Vegas algorithms

Definition 1. A Las Vegas algorithm is a randomized algorithm whose output is always correct.

Randomness is used to upper bound the expected running time of the algorithm.

## Example

Quicksort with random choice of pivot.

## Monte Carlo algorithms

**Definition 2.** • A *Monte Carlo algorithm* is an algorithm whose output is incorrect with probability at most p, 0 .

- A Monte Carlo has *one sided* error if its output is incorrect only on YES-instances or on NO-instances, but not both.
- A one-sided error Monte Carlo algorithm with *false negatives* answers NO for every NO-instance, and answers YES on YES-instances with probability  $p \in (0, 1)$ . We say that p is the *success probability* of the algorithm.

## Boosting success probability

Suppose A is a one-sided Monte Carlo algorithm with false negatives with success probability p. How can we use A to design a new one-sided Monte Carlo algorithm with success probability  $p^* > p$ ?

Let  $t = -\frac{\ln(1-p^*)}{p}$  and run the algorithm t times. Return YES if at least one run of the algorithm returned YES, and No otherwise. Failure probability is

$$(1-p)^t \le (e^{-p})^t = e^{-p \cdot t} = e^{\ln(1-p^*)} = 1-p^*$$

via the inequality  $1 - x \le e^{-x}$ .

**Definition 3.** A randomized algorithm is a one-sided Monte Carlo algorithm with constant success probability.

#### Amplification

**Theorem 4.** If a one-sided error Monte Carlo algorithm has success probability at least p, then repeating it independently  $\left\lceil \frac{1}{p} \right\rceil$  times gives constant success probability.

In particular if we have a polynomial-time one-sided error Monte Carlo algorithm with success probability  $p = \frac{1}{f(k)}$  for some computable function f, then we get a randomized FPT algorithm with running time  $O^*(f(k))$ .

## 2 Vertex Cover

For a graph G = (V, E) a vertex cover  $X \subseteq V$  is a set of vertices such that every edge is adjacent to a vertex in X.

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VERTEX COVERInput:Graph G, integer kParameter:kQuestion:Does G have a vertex cover of size k?
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**Warm-up:** design a randomized algorithm with running time  $O^*(2^k)$ .

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\begin{array}{l} Algorithm \ rvc(G = (V, E), k) \\ S \leftarrow \emptyset \\ \textbf{while} \ k > 0 \ \text{and} \ E \neq \emptyset \ \textbf{do} \\ & \left| \begin{array}{c} \text{Select an edge} \ uv \in E \ \text{uniformly at random} \\ \text{Select an endpoint} \ w \in \{u, v\} \ \text{uniformly at random} \\ & S \leftarrow S \cup \{w\} \\ & G \leftarrow G - w \\ & k \leftarrow k - 1 \\ \textbf{if} \ S \ \text{is a vertex cover of} \ G \ \textbf{then} \\ & {} \ \textbf{return} \ \textbf{YEs} \\ \textbf{else} \\ & {} \ {} \ \textbf{return} \ \textbf{No} \end{array}
```

#### Success probability

- Let C be a minimal vertex cover of G of size k
- What is the probability that Algorithm rvc returns C?
- When it selects an edge  $uv \in E$ , we have that  $\{u, v\} \cap C \neq \emptyset$
- When it selects a random endpoint  $w \in \{u, v\}$ , we have that  $w \in C$  with probability  $\geq 1/2$
- It finds C with probability at least  $1/2^k$

**Theorem 5.** VERTEX COVER has a randomized algorithm with running time  $O^*(2^k)$ .

• If G has vertex cover number at most k, then Algorithm rvc finds one with probability at least  $\frac{1}{2^k}$ .

• Applying Theorem 4 gives a randomized FPT running time of  $O^*(2^k)$ .

# 3 Feedback Vertex Set

A feedback vertex set of a multigraph G = (V, E) is a set of vertices  $S \subset V$  such that G - S is acyclic.

Feedback Vertex Set						
Input:	Multigraph $G$ , integer $k$					
Parameter:	k					
Question:	Does $G$ have a feedback vertex of size $k$ ?					

Recall the following simplification rules for FEEDBACK VERTEX SET.

### Simplification Rules

- 1. Loop: If loop at vertex v, remove v and decrease k by 1
- 2. Multiedge: Reduce the multiplicity of each edge with multiplicity  $\geq 3$  to 2.
- 3. Degree-1: If v has degree at most 1 then remove v.
- 4. Degree-2: If v has degree 2 with neighbors u, w then delete 2 edges uv, vw and replace with new edge uw.

#### The solution is incident to a constant fraction of the edges

**Lemma 6.** Let G be a multigraph with minimum degree at least 3. Then, for every feedback vertex set X of G, at least 1/3 of the edges have at least one endpoint in X.

*Proof.* Denote by n and m the number of vertices and edges of G, respectively. Since  $\delta(G) \geq 3$ , we have that  $m \geq 3n/2$ . Let F := G - X. Since F has at most n - 1 edges, at least  $\frac{1}{3}$  of the edges have an endpoint in X.  $\Box$ 

### **Randomized Algorithm**

**Theorem 7.** FEEDBACK VERTEX SET has a randomized algorithm with running time  $O^*(6^k)$ .

We prove the theorem using the following algorithm.

- $S \leftarrow \emptyset$
- Do k times: Apply simplification rules; add a random endpoint of a random edge to S.
- If S is a feedback vertex set, return YES, otherwise return NO.
- **Proof.** We need to show: each time the algorithm adds a vertex v to S, if (G S, k |S|) is a YES-instance, then with probability at least 1/6, the instance  $(G (S \cup \{v\}), k |S| 1)$  is also a YES-instance. Then, by induction, we can conclude that with probability  $1/(6^k)$ , the algorithm finds a feedback vertex set of size at most k if it is given a YES-instance.
  - Assume (G S, k |S|) is a YES-instance.
  - Lemma 6 implies that with probability at least 1/3, a randomly chosen edge uv has at least one endpoint in some feedback vertex set of size k |S|.
  - So, with probability at least  $\frac{1}{2} \cdot \frac{1}{3} = \frac{1}{6}$ , a randomly chosen endpoint of uv belongs some feedback vertex set of size  $\leq k |S|$ .
  - Applying Theorem 4 gives a randomized FPT running time of  $O^*(6^k)$ .

### Improved analysis

**Lemma 8.** Let G be a multigraph with minimum degree at least 3. For every feedback vertex set X, at least 1/2 of the edges of G have at least one endpoint in X.

**Note:** For a feedback vertex set X, consider the forest F := G - X. The statement is equivalent to:

$$|E(G) \setminus E(F)| \ge |E(F)|$$

Let  $J \subseteq E(G)$  denote the edges with one endpoint in X, and the other in V(F). We will show the stronger result:

$$|J| \ge |V(F)|$$

- *Proof.* Let  $V_{\leq 1}, V_2, V_{\geq 3}$  be the set of vertices that have degree at most 1, exactly 2, and at least 3, respectively, in F.
  - Since  $\delta(G) \geq 3$ , each vertex in  $V_{\leq 1}$  contributes at least 2 edges to J, and each vertex in  $V_2$  contributes at least 1 edge to J.
  - We show that  $|V_{>3}| \le |V_{<1}|$  by induction on |V(F)|.
    - Trivially true for forests with at most 1 vertex.
    - Assume true for forests with at most n-1 vertices.
    - For any forest on *n* vertices, consider removing a leaf (which must always exist) to obtain F' with the vertex partition  $(V'_{\leq 1}, V'_2, V'_{\geq 3})$ . If  $|V_{\geq 3}| = |V'_{\geq 3}|$ , then we have that  $|V_{\geq 3}| = |V'_{\geq 3}| \leq |V'_{\leq 1}| \leq |V_{\geq 1}|$ . Otherwise,  $|V_{\geq 3}| = |V'_{\geq 3}| + 1 \leq |V'_{\leq 1}| + 1 = |V_{\leq 1}|$ .
  - We conclude that:

$$|E(G) \setminus E(F)| \ge |J| \ge 2|V_{\le 1}| + |V_2| \ge |V_{\le 1}| + |V_2| + |V_{\ge 3}| = |V(F)|$$

#### Improved Randomized Algorithm

**Theorem 9.** FEEDBACK VERTEX SET has a randomized algorithm with running time  $O^*(4^k)$ .

### Note

This algorithmic method is applicable whenever the vertex set we seek is incident to a constant fraction of the edges.

# 4 Color Coding

### Longest Path

LONGEST PAT	Longest Path				
Input:	Graph $G$ , integer $k$				
Parameter:	k				
Question:	Does $G$ have a path on $k$ vertices as a subgraph?				

### NP-complete

To show that LONGEST PATH is NP-hard, reduce from HAMILTONIAN PATH by setting k = n and leaving the graph unchanged.

Color Coding Notation:  $[k] = \{1, 2, \dots, k\}$ 

**Lemma 10.** Let U be a set of size n, and let  $X \subseteq U$  be a subset of size k. Let  $\chi : U \to [k]$  be a coloring of the elements of U, chosen uniformly at random. Then the probability that the elements of X are colored with pairwise distinct colors is at least  $e^{-k}$ .

*Proof.* There are  $k^n$  possible colorings  $\chi$  and  $k!k^{n-k}$  of them are injective on X. Using the inequality

$$k! > (k/e)^k.$$

the lemma follows since

$$\frac{k! \cdot k^{n-k}}{k^n} > \frac{k^k \cdot k^{n-k}}{e^k \cdot k^n} = e^{-k}.$$

Colorful Path

A path is *colorful* if all vertices of the path are colored with pairwise distinct colors.

**Lemma 11.** Let G be an undirected graph, and let  $\chi : V(G) \to [k]$  be a coloring of its vertices with k colors. There is an algorithm that checks in time  $O^*(2^k)$  whether G contains a colorful path on k vertices.

*Proof.* Partition V(G) into  $V_1, ..., V_k$  subsets such that vertices in  $V_i$  are colored *i*.

Apply dynamic programming on nonempty  $S \subseteq \{1, ..., k\}$ . For  $u \in \bigcup_{i \in S} V_i$  let P(S, u) = true if there is a colorful path with colors from S and u as an endpoint. We have the following:

- For |S| = 1, P(S, u) = true for  $u \in V(G)$  iff  $S = \{\chi(u)\}$ .
- For |S| > 1

$$P(S, u) = \begin{cases} \bigvee_{uv \in E(G)} P(S \setminus \{\chi(u)\}, v) & \text{ if } \chi(u) \in S\\ false & \text{ otherwise} \end{cases}$$

All values of P can be computed in  $O^*(2^k)$  time and there exists a colorful k-path iff P([k], v) is true for some vertex  $v \in V(G)$ .

**Theorem 12.** LONGEST PATH has a randomized algorithm with running time  $O^*((2 \cdot e)^k)$ .

#### Note

This algorithmic method is applicable whenever we seek a vertex set S of size f(k) such that G[S] has constant treewidth.

## 5 Monotone Local Search

Exponential-time algorithms	Parameterized algorithms		
• Algorithms for NP-hard problems	• Algorithms for NP-hard problems		
• Beat brute-force & improve	• Use a parameter $k$		
• Running time measured in the size of the universe	(often $k$ is the solution size)		
n	• Algorithms with running time $f(k) \cdot n^c$		
• $O(2^n \cdot n), O(1.5086^n), O(1.0892^n)$	• $k^k n^{O(1)}, 5^k n^{O(1)}, O(1.2738^k + kn)$		
Can we use Parameterized algorithms to design fast Exponential-time algorithms?			

## Example: Feedback Vertex Set

 $S \subseteq V$  is a feedback vertex set in a graph G = (V, E) if G - S is acyclic.

FEEDBACK VERTEX SETInput:Graph G = (V, E), integer kParameter:kQuestion:Does G have a feedback vertex set of size at most k?



Exponential-time algorithms

- $O^*(2^n)$  trivial
- $O(1.7548^n)$  [Fom+08]
- $O(1.7347^n)$  [FV10]
- $O(1.7266^n)$  [XN15]

- Parameterized algorithms
  - $O^*((17k^4)!)$  [Bod94]
  - $O^*((2k+1)^k)$  [DF99] :
  - $O^*(3.460^k)$  deterministic [IK19]
  - $O^*(2.7^k)$  randomized [LN19]

## Exponential-time algorithms via parameterized algorithms

## **Binomial** coefficients

$$\underset{0 \le k \le n}{\operatorname{arg\,max}} \binom{n}{k} = n/2 \quad \text{and} \quad \binom{n}{n/2} = \Theta(2^n/\sqrt{n})$$

### Algorithm for Feedback Vertex Set

- Set  $t=0.60909\cdot n$
- If  $k \leq t$ , run  $O^*(3^k)$  algorithm
- Else check all  $\binom{n}{k}$  vertex subsets of size k

Running time:  $O^*\left(\max\left(3^t, \binom{n}{t}\right)\right) = O^*(1.9526^n)$ 

This approach gives algorithms faster than  $O^*(2^n)$  for subset problems with a parameterized algorithm faster than  $O^*(4^k)$ .

## Subset Problems

An *implicit set system* is a function  $\Phi$  with:

- Input: instance  $I \in \{0, 1\}^*, |I| = N$
- Output: set system  $(U_I, \mathcal{F}_I)$ :
  - universe  $U_I$ ,  $|U_I| = n$
  - family  $\mathcal{F}_I$  of subsets of  $U_I$

## Φ-Subset

Input: Instance I Question: Is  $|\mathcal{F}_I| > 0$ ?

 $\Phi$ -Extension

Input: Instance I, a set  $X \subseteq U_I$ , and an integer k Question: Does there exist a subset  $S \subseteq (U_I \setminus X)$  such that  $S \cup X \in \mathcal{F}_I$  and  $|S| \leq k$ ?

### Algorithm

Suppose  $\Phi$ -EXTENSION has a  $O^*(c^k)$  time algorithm B.

Algorithm for checking whether  $\mathcal{F}_I$  contains a set of size k

- Set  $t = \max\left(0, \frac{ck-n}{c-1}\right)$
- Uniformly at random select a subset  $X \subseteq U_I$  of size t
- Run B(I, X, k-t)

Running time: [Fom+19]

$$O^*\left(\frac{\binom{n}{t}}{\binom{k}{t}} \cdot c^{k-t}\right) = O^*\left(2 - \frac{1}{c}\right)^n$$

## Intuition

### Brute-force randomized algorithm

- Pick k elements of the universe one-by-one.
- Suppose  $\mathcal{F}_I$  contains a set of size k.

Success probability:

$$\frac{k}{n} \cdot \frac{k-1}{n-1} \cdot \dots \cdot \frac{k-t}{n-t} \cdot \dots \cdot \frac{2}{n-(k-2)} \frac{1}{n-(k-1)} = \frac{1}{\binom{n}{k}}$$

$$\parallel \frac{1}{c}$$

**Theorem 13** ([Fom+19]). If there exists a (randomized) algorithm for  $\Phi$ -EXTENSION with running time  $O^*(c^k)$  then there exists a randomized algorithm for  $\Phi$ -SUBSET with running time  $(2 - \frac{1}{c})^n \cdot N^{O(1)}$ .

**Theorem 14** ([Fom+19]). FEEDBACK VERTEX SET has a randomized algorithm with running time  $O^*\left(\left(2-\frac{1}{2.7}\right)^n\right) \subseteq O(1.6297^n)$ .

### Derandomization

Derandomization at the expense of a subexponential factor in the running time.

**Theorem 15** ([Fom+19]). If there exists an algorithm for  $\Phi$ -EXTENSION with running time  $O^*(c^k)$  then there exists an algorithm for  $\Phi$ -SUBSET with running time  $(2 - \frac{1}{c})^{n+o(n)} \cdot N^{O(1)}$ .

**Theorem 16** ([Fom+19]). FEEDBACK VERTEX SET has an algorithm with running time  $O^*\left(\left(2-\frac{1}{3.460}\right)^n\right) \subseteq O(1.7110^n)$ .

### **Further Reading**

- Chapter 5, Randomized methods in parameterized algorithms by [Cyg+15]
- Exact Algorithms via Monotone Local Search [Fom+19]

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