SEARCHING AND TREES

o COMP1927 Computing 17x1o Sedgewick Chapters 5, 12

SEARCHING (CONT)

Searching is a very important/frequent operation. Several approaches have been developed:

- *O(n)* ... linear scan (search technique of last resort)
- *O(logn)* ... binary search, **search trees** (trees also have other uses)
- *O(1)* ... hash tables (only *O(1)* under optimal conditions)

SEARCHING (CONT)

Linear structures: arrays, linked lists

- Arrays = random access.
- Lists = sequential access.

	Array	List
Unsorted	O(n) (linear scan)	O(n) (linear scan)
Sorted	O(log n) (binary search)	O(n) (linear scan)

SEARCHING

o Storing and searching sorted data:

o Dilemma: Inserting into a sorted sequence

- Finding the insertion point on an array O(log n) but then we have to move everything along to create room for the new item
- Finding insertion point on a linked list O(n) but then we can add the item in constant time.

o Can we get the best of both worlds?

TREE TERMINOLOGY

Trees are branched data structures

- **o** consisting of *nodes (vertices)* and *links (edges)*, with no cycles
- **o** each node contains a *data* value (or key + data)
- **o** each node has links to $\leq k$ other nodes (k=2 below)



TREES

• Trees can be viewed as a set of nested structures: each node has *k* possibly empty subtrees



USES OF TREES

- Trees are used in many contexts, e.g. representing hierarchical data structures (e.g. expressions)
- **o** efficient searching (e.g. sets, symbol tables, ...)



TREE TERMINOLGY

• Level of a node in a tree (or depth) is one higher than the level of its parent

- Depth of the root is 0
- **o** We call the length of the longest path from the root to a node the height of a tree



SPECIAL PROPERTIES OF SOME TREES

- M-ary tree: each internal node has exactly M children
- Ordered tree: order of the children at every node is specified through constraints on the data/keys in the nodes
- **o Balanced tree**: a tree with properties that
 - #nodes in left subtree = #nodes in right subtree
 - this property applies over all nodes in the tree

BINARY TREES

For much of this course, we focus on *binary trees*

A *binary tree* (simplest type of M-ary tree) is defined recursively, as being either:

- empty (contains no nodes)
- consisting of a node, with two sub-trees
 - each node contains a value
 - the left and right sub-trees are *binary trees*

BINARY TREES: PROPERTIES

- A binary tree with *n* nodes has a height of
 - at most
 - n-1 (if degenerate) (an unbalanced tree, where for each parent node, there is only one child node)
 - at least
 - floor(log₂(n)) (if balanced)





BINARY SEARCH TREE (BST)

o A BST is an **ordered binary tree** that has:

- all values in left sub-tree being less than root
- all values in right sub-tree are greater than root
- this property applies over all nodes in the tree
- each node is the root of 0, 1 or 2 sub-trees



BINARY TREES

Shape of tree is determined by the order of insertion





BINARY SEARCH TREES

Depth of tree = max path length from root to leaf



Depth of tree with n nodes: min = floor(log₂n), max = n-1 Height balanced tree: ∀ nodes, depth(left subtree) ≅ depth(right subtree)
Time complexity of tree algorithms is typically O(depth)

EXERCISE: INSERTION INTO BSTS

- For each of the sequences below start from an initially empty binary search tree
 - show the tree resulting from inserting the values in the order given
 - What is the height of each tree?
- **o**(a) 4 2 6 5 1 7 3
- **o** (b) 5 3 6 2 4 7 1
- **o**(c) 1 2 3 4 5 6 7

TREES: TRAVERSAL

o For trees, several well-defined visiting orders exist:

- Depth first traversals
 - •preorder (NLR) ... visit root, then left subtree, then right subtree
 - oinorder (LNR) ... visit left subtree, then root, then right subtree
 - •postorder (LRN) ... visit left subtree, then right subtree, then root
- Breadth-first traversal or level-order ... visit root, then all its children, then all their children

EXAMPLE OF TRAVERSALS ON A BINARY TREE



Representing BSTs

A binary search tree is a generalization of a linked list:

- nodes are a structure with two links to nodes
- empty trees are NULL links

typedef struct treenode *Treelink;

```
struct treenode {
    int data;
    Treelink left, right;
```

REPRSENTING BSTS

Abstract data vs concrete data



BINARY SEARCH TREES

Operations on BSTs:

- traverse(TreeLink, (*visit)) ... traverse tree
- insert(TreeLink, Item) ... add new item to tree via key
- delete(TreeLink, Item) ... remove item with specified key from tree
- search(TreeLink,Item) ... find item containing key in tree
- height(TreeLink) ... compute depth of tree
- nodes(TreeLink) ... count #nodes in tree
- plus, "bookeeping" ... new(), dispose(), show(), empty(), ...
- **Notes:** keys are unique (not technically necessary)

BINARY SEARCH TREES

Traversal (with parameterised visit option) void traverse(TreeLink t, void (*visit)(Item)) {

if (t == null) return; (*visit)(t); // NLR traversal traverse(t->left, visit); // put "visit data" here for LNR traverse(t->right, visit); // put "visit data" here for LRN

SEARCHING IN BSTS

o Recursive version

```
// Returns non-zero if item is found,
// zero otherwise
int search(TreeLink n, Item i) {
    int result;
    if(n == NULL) {
      result = 0;
    }else if(i < n->data){
       result = search(n->left,i);
    }else if(i > n->data)
       result = search(n->right,i);
    }else{ // you found the item
      result = 1;
    return result;
```

* Exercise: Try writing an iterative version

INSERTION INTO A BST

• Cases for inserting value V into tree T:

- T is empty, make new node with V as root of new tree
- root node contains V, tree unchanged (no dups)
- V < value in root, insert into left subtree (recursive)
- V > value in root, insert into right subtree (recursive)
- **o** Non-recursive insertion of V into tree T:
 - search to location where V belongs, keeping parent
 - make new node and attach to parent
 - whether to attach $L \mbox{ or } R$ depends on last move

INSERTION INTO A BST

```
//Returns the root of the tree
```

//Inserts duplicates on the left hand side of tree

```
Treelink insertRec (Treelink tree, TreeItem item) {
```

if(tree == NULL){

```
Treelink newNode = createNode(item);
```

```
return newNode; //now the root of the tree
```

```
else \{
```

```
if(item <= tree->item){
    tree->left = insertRec(tree->left, item); //
} else {
    tree->right = insertRec(tree->right, item);
}
```

return tree;

o Insertion into a binary search tree is easy:

- find location in tree where node to be added
- create node and link to parent
- **o** Deletion from a binary search tree is harder:
 - find the node to be deleted and its parent
 - unlink node from parent and delete
 - replace node in tree by ... ???

- Easy option ... don't delete; just mark node as deleted
 - future searches simply ignore marked nodes
- **o** If we want to delete, three cases to consider ...
 - zero subtrees ... unlink node from parent
 - one subtree ... replace node by child
 - two subtrees ... two children; one link in parent

• Case 1: value to be deleted is a leaf (zero subtrees)



• Case 1: value to be deleted is a leaf (zero subtrees)



• Case 2: value to be deleted has one subtree



• Case 2: value to be deleted has one subtree



o Case 3a: value to be deleted has two subtrees

- Replace deleted node by its immediate successor
 - The smallest (leftmost) node in the right subtree



 \boldsymbol{o} Case : value to be deleted has two subtrees



BINARY SEARCH TREE PROPERTIES

- Cost for searching/deleting:
 - Worst case: key is not in BST search the height of the tree

 ${\sf o} \ Balanced \ trees - O(log_2n)$

o Degenerate trees – O(n)

- Cost for insertion:
 - Always traverse the height of the tree • Balanced trees $-O(log_2n)$ • Degenerate trees -O(n)

NEW BINARY SEARCH TREE

// Item, Key, Node, Link, Tree types as before #define key(it) ((it).key) // operations on keys #define cmp(k1,k2) ((k1) - (k2)) #define lt(k1,k2) (cmp(k1,k2) < 0) #define eq(k1,k2) (cmp(k1,k2) == 0) #define gt(k1,k2) (cmp(k1,k2) > 0) // standard tree operations Tree newTree(); Tree insert(Tree, Item); Tree delete(Tree, Key); int find(Tree, Key);

INSERTION USING NEW TREE ADT

- // more standard tree operations void dropTree(Tree); void showTree(Tree); int depth(Tree); int nnodes(Tree); // aka size() // functions internal to ADT Link rotateR(Link); Link rotateL(Link); **Tree insertAtRoot(Tree, Item);**
- Tree insertRandom(Tree, Item);

INSERT AT ROOT - ROTATE OPERATIONS



INSERT AT ROOT - ROTATE OPERATIONS



```
Link rotateR(Link n1) {
    if (n1 == NULL) return NULL;
    Link n2 = n1->left;
    if (n2 == NULL) return n1;
    n1->left = n2->right;
    n2->right = n1;
    return n2;
}
```

Left rotation is similar with n1/n2 and left/right switched

INSERTION AT ROOT

- Previous description of BSTs inserted at leaves.
- **o** Different approach: insert new value at root.
- **o** Method for inserting at root (recursive):
- **o** base case:
 - tree is empty; make new node and make it root
- **o** recursive case:
 - insert new node as root of L/R subtree
 - lift new node to root by R/L rotation

INSERTION AT ROOT



INSERTION AT ROOT (CONT)

```
Tree insertAtRoot(Tree t, Item it) {
  if (t == NULL) return newNode(item);
  int diff = cmp(key(it), key(t->value));
  if (diff == 0) t->value = it;
  else if (diff < 0)
      t->left = insertAtRoot(t->left, it);
      t = rotateR(t);
   else if (diff > 0) {
      t->right = insertAtRoot(t->right, it);
      t = rotateL(t);
return t;
```