

# COMP9444

## Neural Networks and Deep Learning

### 3c. PyTorch

#### Typical Structure of a PyTorch Program

```
# create neural network
net = MyNetwork().to(device) # CPU or GPU

train_loader = torch.utils.data.DataLoader(....)
test_loader = torch.utils.data.DataLoader(....)

# choose between SGD, Adam or other optimizer
optimizer = torch.optim.SGD(net.parameters,....)

for epoch in range(1, epochs):
    train(args, net, device, train_loader, optimizer)
    test( args, net, device, test_loader)
```

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#### Defining a Network Structure

```
class MyNetwork(torch.nn.Module):

    def __init__(self):
        super(MyNetwork, self).__init__()
        # define structure of the network here

    def forward(self, input):
        # apply network and return output
```

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#### Training

```
def train(args, net, device, train_loader, optimizer):

    for batch_idx, (data,target) in enumerate(train_loader):
        optimizer.zero_grad() # zero the gradients
        output = net(data) # apply network
        loss = ... # compute loss function
        loss.backward() # compute gradients
        optimizer.step() # update weights
```

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## Testing

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```
def test(args, model, device, test_loader):

    with torch.no_grad(): # suppress updating of gradients
        net.eval() # toggle batch norm, dropout
        for data, target in test_loader:
            output = model(data)
            test_loss = ...
            print(test_loss)
        net.train() # toggle batch norm, dropout back again
```